

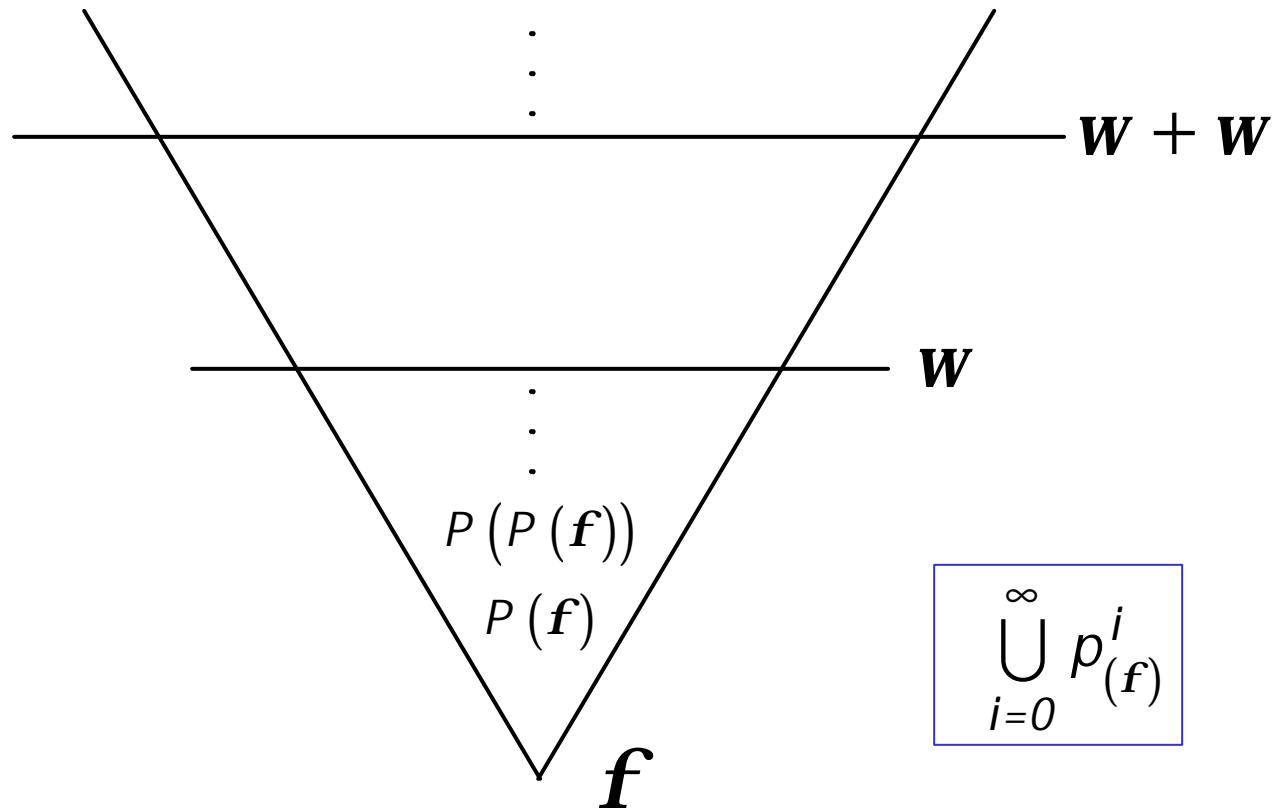
Lecture 2

Set Theoretic Semantics for Type Theory

Marktoberdorf Summer School, 2003



The Cumulative Hierarchy of Sets



Captures the intuition of collecting stages and co-finality...
unending stages.

Zermelo Fraenkel Set Theory (ZF)

ZF can be axiomatized in 1st order logic by axioms, 2 axiom schemas (separation, replacement). Axiom of choice is a 9th axiom.

The hierarchy is defined as:

$$Z_0 = \mathbf{f}$$

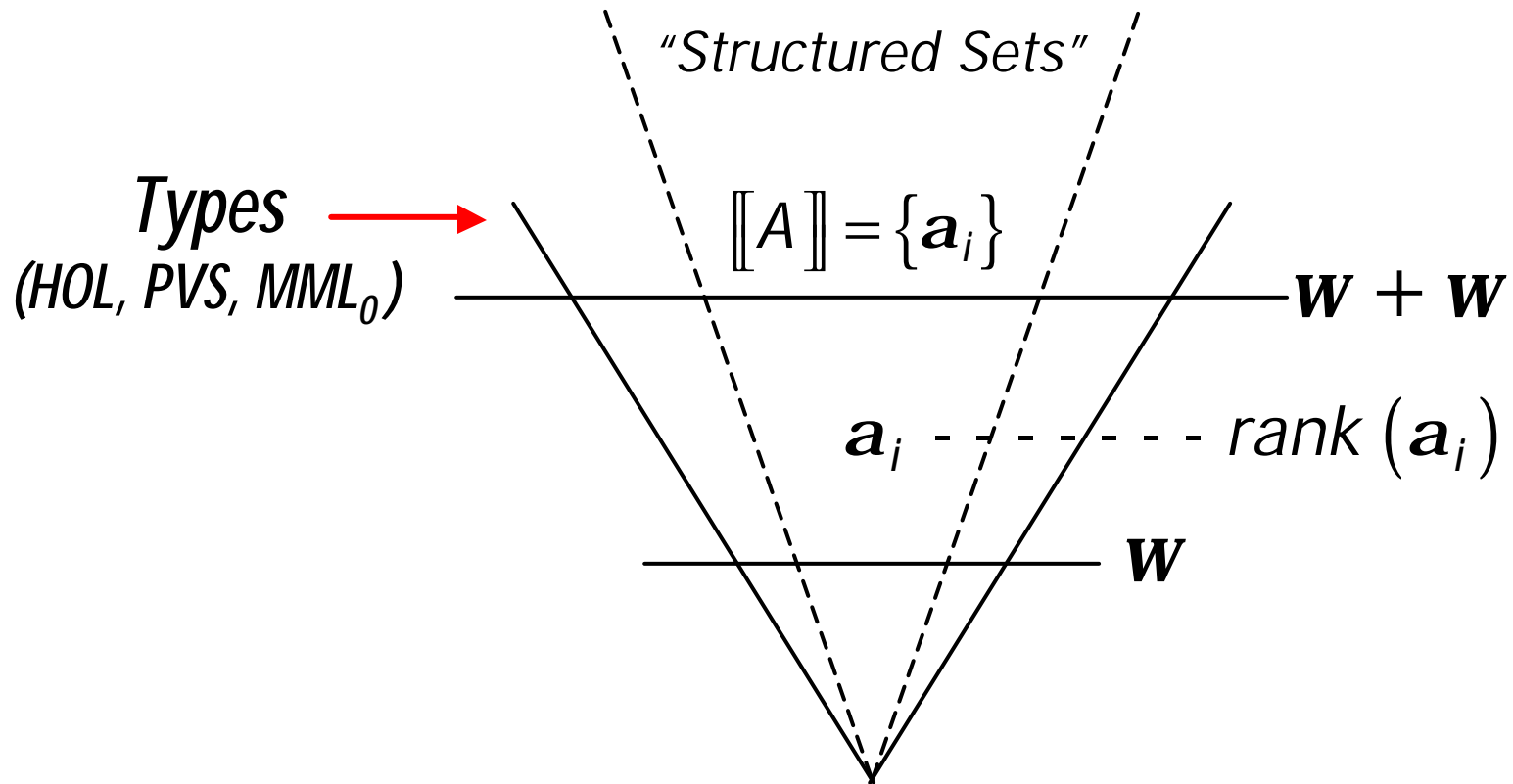
$$Z_a = \bigcup_{b < a} Z_b$$

$$Z_{a+1} = P(Z_a)$$

$$Z = \bigcup_{a \text{ Ord}} Z_a$$

Every ZF set x is in some Z_α ; its rank is the least such ordinal α .

Review of Set Theoretic Semantics



The Cumulative Hierarchy of Sets

Goal of Howe's Approach

Pure
Type Theory

$$\begin{array}{c}
 \boxed{a_1, a_2, \dots, a_i \dots} \\
 f(a) \\
 f \Downarrow \mathbf{I}x.b \quad p \Downarrow \langle a, b \rangle \\
 \hline
 \mathbf{I}x.b \quad \langle a, b \rangle \quad c_i(\bar{a}) \quad \cup_i
 \end{array}$$

enlarge
↓

Type Theory
with
Set Terms

$$\begin{array}{c}
 \boxed{a_1, a_2, \dots, a_i \dots} \quad \boxed{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_i \dots} \\
 A \quad \hat{\mathbf{g}}_A \quad f(a) \quad \hat{\mathbf{j}}(\hat{\mathbf{a}}) \\
 f \Downarrow \mathbf{I}x.b \quad f \Downarrow \hat{\mathbf{j}} \quad c_i(\bar{a}) \Downarrow c_i(\hat{\mathbf{a}}) \\
 \hline
 \mathbf{I}x.b \quad a \mapsto b \quad \langle a, b \rangle \quad \langle \hat{\mathbf{a}}, \hat{\mathbf{b}} \rangle \quad c_i(\bar{a}) \quad c_i(\hat{\mathbf{a}})
 \end{array}$$

Howe's Meaning Functions

Howe's Approach to Set-theoretic Semantics:

Like Pitts, Dybjer, Troelstra and other, Doug Howe maps types into sets; for A , a type,

$\llbracket A \rrbracket$ is a set.

However, he introduces new ideas to handle functionality, **polymorphism**, subtyping, quotient types, and types as objects (universes). For instance,

$\llbracket \lambda x.x \rrbracket_{A \rightarrow A}$ is an element \mathbf{j} of $\llbracket A \rightarrow A \rrbracket$

and he writes that $\mathbf{j} \triangleleft \lambda x.x$.

Limitations of Set Embedding

Unlike with PVS and HOL, no embedding can cover all of Nuprl because

- Recursive types allow $T = (T \rightarrow \mathbb{B}) \rightarrow \mathbb{B}$
- Domains all absolutely **unsolvable problems**

But Howe gets a very substantial part and Moran extends to more. This raises the issue of sub-theories of domains and recursive types.

Goal of Howe's Approach

- Extend the family of "structured sets"
- Create constants for all "structured sets"
- Extend evaluation to all terms
- Define approximation (covering)

$$\mathbf{a}_i \triangleleft a_i$$

to relate sets \mathbf{a}_i to terms a_i

Howe's Method

1. **Encode** type terms and types into sets in the cumulative hierarchy

W

$\langle ty, \mathbf{g} \rangle$

\mathbf{g}

$\langle fn, \mathbf{j} \rangle$

\mathbf{j}

$\langle c_i \langle \mathbf{a}_1, \dots, \mathbf{a}_n \rangle \rangle$

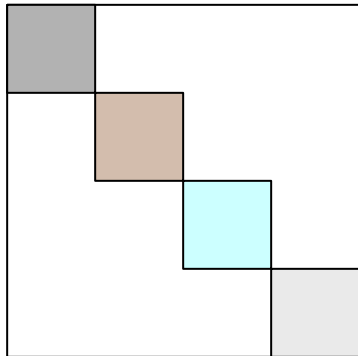
$c_i(\bar{\mathbf{a}})$

2. Define a subset of W with a **unique meaning** property; call it V .
3. Define a **term model** for all V sets; call it T_0 .
4. Define evaluation and approximation on T_0 ; this provides a computational type theory with **set oracles**.

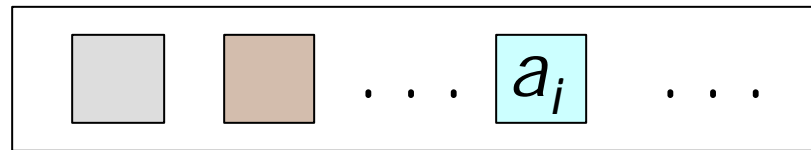
I present a variant used by Evan Moran to extend Howe's results.

Howe's Semantics

We think of types as collections of equivalence classes of terms:



or



We need to allow sets representing equivalence classes \mathbf{a}_i into types

$$\boxed{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n} \text{ written } \mathbf{g}\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$$

where \mathbf{a}_i covers a_i (\mathbf{a}_i approximates a_i) $\mathbf{a}_i \triangleleft a_i$

Disjointness and Incompatibility

The equivalence classes are **disjoint**, of course.

$$A = \boxed{a_1 \quad a_2 \quad \dots \quad a_i \quad \dots}$$

$$\text{if } a_i \cap a_j \neq 0 \text{ then} \\ a_i = a_j$$

The set elements must also be **incompatible**:

$$\mathbf{g}_A = \{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_i\}$$

$$\text{con}(\mathbf{a}_i, \mathbf{a}_j) \text{ implies } \mathbf{a}_i = \mathbf{a}_j$$

For each $a_i \in A$ there will be a **unique** $\mathbf{a}_i \in \mathbf{g}_A$, $\mathbf{a}_i \triangleleft a_i$.

Disjointness and Incompatibility

The key condition for functions is:

$$\mathbf{j} \quad \langle \mathbf{a}_1, \mathbf{b}_1 \rangle, \langle \mathbf{a}_2, \mathbf{b}_2 \rangle, \dots, \langle \mathbf{a}_i, \mathbf{b}_i \rangle, \dots$$

$$\mathbf{j}' \quad \langle \mathbf{a}'_1, \mathbf{b}'_1 \rangle, \langle \mathbf{a}'_2, \mathbf{b}'_2 \rangle, \dots, \langle \mathbf{a}'_i, \mathbf{b}'_i \rangle, \dots$$

If for all $\langle \mathbf{a}, \mathbf{b} \rangle, \langle \mathbf{a}', \mathbf{b}' \rangle$
 $con(\mathbf{a}_i, \mathbf{a}'_i)$ implies $con(\mathbf{b}_i, \mathbf{b}'_i)$
then
 $con(\mathbf{j}, \mathbf{j}')$

Compatibility (Consistency) Examples

- $0 \mapsto 0$ and $1 \mapsto 1$ are **compatible** (consistent) since $\mathbf{j} \{ \langle 0, 0 \rangle \}$ and $\mathbf{j} \{ \langle 1, 1 \rangle \}$ have a non-empty intersection, $\mathbf{j} \{ \langle 0, 0 \rangle, \langle 1, 1 \rangle \}$.
- $0 \mapsto (0 \mapsto 0)$ and $0 \mapsto (1 \mapsto 1)$ are **compatible**,
 i.e. $\mathbf{j} \{ \langle 0, \mathbf{j} \{ \langle 0, 0 \rangle \} \rangle \}$ **con** $\mathbf{j} \{ \langle 0, \mathbf{j} \{ \langle 1, 1 \rangle \} \rangle \}$
 since 0 **con** 0 and $\mathbf{j} \{ \langle 0, 0 \rangle \}$ **con** $\mathbf{j} \{ \langle 1, 1 \rangle \}$.

Membership and Approximation

If the type A is interpreted as the set \mathbf{g}_A , then for each $a \in A$, there is a unique \mathbf{a} such that

$$\mathbf{a} \triangleleft a.$$

We will say $\llbracket A \rrbracket = \mathbf{g}_A$ and $\llbracket a \rrbracket_A = \mathbf{a}$.

Uniqueness Theorem

For any term t in T_0 ,

1. If $g_1 \triangleleft t$ and $g_2 \triangleleft t$, then $g_1 = g_2$
2. For all $g \in V$ and $a_1, a_2 \in g$,
if $a_1 \triangleleft t$ and $a_2 \triangleleft t$, then $a_1 = a_2$

The Term Language T_0

Howe defines a term language, T_0 , that includes the Nuprl terms with binding, such as

$$x : A \rightarrow B, x : A \times B, \mathbf{I} x . b, x : A \cap B, \\ \text{less } (n; m; a; b), \text{decide } (p; x . a; y . b), \dots$$

T_0 includes the constructors and constants, such as

$$\mathbb{U}_i, \text{nat } \{n\}, \text{pair } (a; b), \text{inl } (a), \text{inr } (b), \text{ap } (f; a), \dots$$

T_0 includes constants for all of the $\mathbf{g}, \mathbf{j}, \mathbf{x}, c_i, (\bar{\mathbf{a}})$ sets.
Howe uses $\hat{\mathbf{g}}, \hat{\mathbf{j}}, \hat{\mathbf{x}}$ to denote the set terms.

The Term Language T_0

Howe extends the evaluation relation to all terms, for example:

$$\begin{aligned} ap(\mathbf{1}x.b; a) \Downarrow c & \text{ if } b[a/x] \Downarrow c \\ less(0;1;a;b) \Downarrow c & \text{ if } a \Downarrow c \end{aligned}$$

For instance, $ap(\mathbf{1}x.x;\hat{j}) \Downarrow \hat{j}$.

Evaluation Rules

$$\frac{f \Downarrow \hat{f} \quad (a, b) ? f \quad a \triangleleft a}{f(a) \Downarrow \hat{b}} \quad (ap_f) \quad \frac{f \Downarrow \lambda x. b \quad b[a/x] \Downarrow v}{f(a) \Downarrow v} \quad (ap_1)$$

$$\overline{\hat{g} \Downarrow \hat{g}}$$

$$\overline{\lambda x. b \Downarrow \lambda x. b}$$

$$\overline{c_i(\bar{a}) \Downarrow c_i(\bar{a})}$$

Approximation Rules

$$\frac{e \Downarrow v \quad \mathbf{a} \triangleleft v}{\mathbf{a} \triangleleft e} \quad \frac{?j \quad \mathbf{a}_j \triangleleft a_j}{c_i(\hat{\mathbf{a}}_1, \dots, \hat{\mathbf{a}}_n) \triangleleft c_i(\hat{a}_1, \dots, \hat{a}_n)}$$

$$\frac{?(a, b) \quad ?f \quad \mathbf{b} \triangleleft b \left[\hat{\mathbf{a}} / x \right]^\dagger}{f \triangleleft l x . b}$$

† Howe does not use this rule because it is unproven when the **non-determinism** of functions on quotient types is allowed.

Examples

$$\text{Let } \mathbf{j} = \{ \langle 0, 4 \rangle, \langle 1, 5 \rangle \} \quad \mathbf{j}' = \{ \langle 0, 2 \rangle \}$$
$$\mathbf{y} = \{ \langle \mathbf{j}, 17 \rangle, \langle \mathbf{j}', 18 \rangle \}$$

$$\hat{\mathbf{j}}(0 + 0) \Downarrow 4 \quad \text{because } 0 \triangleleft 0 + 0$$

$$\hat{\mathbf{j}} \triangleleft \mathbf{1}x.x + 4 \quad \text{but not } \hat{\mathbf{j}}' \triangleleft \mathbf{1}x.x + 4$$

$$\hat{\mathbf{y}}(\mathbf{1}x.x + 4) \Downarrow 17$$

The Substitution Lemma

If $\mathbf{a} \triangleleft a$ then for any term e ,
 $\mathbf{b} \triangleleft e[\mathbf{a} / x]$ implies $\mathbf{b} \triangleleft e[a / x]$

The intuition is that for any demonstration of $\mathbf{b} \triangleleft e[\mathbf{a} / x]$, if it does not examine \mathbf{a} , then it also establishes $\mathbf{b} \triangleleft e[a / x]$.

If the derivation depends on \mathbf{a} , then since $\mathbf{a} \triangleleft a$ and a is a term, there is more information in a than in any approximation \mathbf{a} , and that information will establish the facts used about \mathbf{a} to show $\mathbf{b} \triangleleft e[\mathbf{a} / x]$ using a in place of \mathbf{a} .

See [Working Material](#), Lemma 2.4, p. 25.

Rationale for the Substitution Lemma

Assume $\mathbf{a} \triangleleft a$ and $\mathbf{b} \triangleleft e \left[\hat{\mathbf{a}} / x \right]$

To say $\mathbf{b} \triangleleft e \left[\hat{\mathbf{a}} / x \right]$ means $\mathbf{a} \mapsto \mathbf{b} \triangleleft \mathbf{l} x . e$.

Thus, $\mathbf{l} x . e \ ? \ \mathbf{g} \{ \mathbf{a} \mapsto \mathbf{b} \}$, a **singleton set**, and

$$(1) \ \mathbf{l} x . e \in \mathbf{g} \{ \mathbf{a} \} \rightarrow \mathbf{g} \{ \mathbf{b} \}$$

$$(2) \ \text{From } \mathbf{a} \triangleleft a \text{ we know } a \ ? \ \mathbf{g} \{ \mathbf{a} \}$$

From (1) and (2) we have $(\mathbf{l} x . e) a \ ? \ \mathbf{g} \{ \mathbf{b} \}$,

thus, $e \left[a / x \right] \ ? \ \mathbf{g} \{ \mathbf{b} \}$, and hence

$$\mathbf{b} \triangleleft e \left[a / x \right].$$

Interpreting Sequents

Given a sequent $x_1 : A_1, \dots, x_n : A_n \vdash g \ ? \ G$,
a **closing substitution** cl for it is a sequence of closed
terms

$$a_1, \dots, a_n \text{ for } x_1, \dots, x_n.$$

The x_i are the only free variables in g and G .

The **sequent is true** iff $\llbracket cl(g) \rrbracket_{cl(G)}$ is defined and
belongs to $\llbracket cl(G) \rrbracket$ for all closing substitutions cl such that

$$\llbracket cl(x_i) \rrbracket_{cl(A_i)} \ ? \ \llbracket cl(A_i) \rrbracket.$$

Interpreting Rules

Given sequents s, s_1, \dots, s_k , the rule

$$\frac{s_1, \dots, s_k}{s}$$

is **sound** if the conclusion s is true whenever the premises s_i are true.

Soundness of Core Nuprl in Howe's Semantics

The function elimination rule – no hypotheses case:

$$\frac{\vdash a ? A \quad \vdash f ? (x : A \rightarrow B)}{\vdash f (a) ? B [a / x]}$$

Soundness – the Meaning of $x : A \textcircled{R} B$

Recall from the Working Material:

$\llbracket x : A \rightarrow B \rrbracket$ is the set of functions \mathbf{j} with domain $\llbracket A \rrbracket$ such that for all $\langle \mathbf{a}, \mathbf{b} \rangle \in \mathbf{j}$,
 $\mathbf{b} \in \llbracket B [\mathbf{a} / x] \rrbracket = \mathbf{g}_{\mathbf{a}}$.

Soundness of Function Elimination – the Premises

The premise $\vdash a ? A$ is true in Howe's model provided

$$\llbracket A \rrbracket = \mathbf{g} \text{ and } \llbracket a \rrbracket_A = \mathbf{a} \text{ and } \mathbf{a} ? \mathbf{g}.$$

The premise $f ? (x : A \rightarrow B)$ is true if

$$\llbracket f \rrbracket_{x:A \rightarrow B} = \mathbf{j}_f \text{ is in } \llbracket x : A \rightarrow B \rrbracket.$$

Soundness of Function Elimination – the Conclusion

We need to know that $\llbracket f(a) \rrbracket_{B[a/x]}$ is defined, i.e.

there is a \mathbf{b} in $\llbracket B[a/x] \rrbracket$

$$\mathbf{b} \triangleleft \llbracket f(a) \rrbracket.$$

We know that for any $\langle \mathbf{a}, \mathbf{b} \rangle \in \mathbf{j}_f$, $\mathbf{b} \in \llbracket B[\hat{\mathbf{a}}/x] \rrbracket$,
by the premise for f .

To say $\llbracket a \rrbracket_A = \mathbf{a}$ means $\mathbf{a} \triangleleft a$. (Recall
"Membership and Approximation.")

Soundness of Function Elimination – the Conclusion

By the **Substitution Lemma**,

if $\mathbf{g} \triangleleft B [\hat{\mathbf{a}} / x]$, then $\mathbf{g}_a \triangleleft B [a / x]$,

thus, $\mathbf{g} = \llbracket B [\hat{\mathbf{a}} / x] \rrbracket = \llbracket B [a / x] \rrbracket$.

Likewise, if $\mathbf{b} \triangleleft f (\hat{\mathbf{a}})$ then $\mathbf{b} \triangleleft f (a)$.

But **by the Substitution Lemma**, we know $\mathbf{b} \triangleleft f (\hat{\mathbf{a}})$,
since $\mathbf{j}_f \triangleleft f$ and $\mathbf{b} \triangleleft \mathbf{j}_f (\hat{\mathbf{a}})$.

Hence $\llbracket f (a) \rrbracket_{B[a/x]} ? \llbracket B [a / x] \rrbracket$ as required.