

Synthetic Topology in NuPRL

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What is Synthetic Topology?

Branch of topology, designed to export topological results into other fields.

Escardó, Martín. 2004. *Synthetic Topology of Data Types and Classical Spaces*. ENTCS 87.

What is Synthetic Topology?

- “1. to explain what has been done in classical topology in conceptual terms,
2. to provide one-line, enlightening proofs of the theorems that constitute the core of the theory, and
3. to smoothly export topological concepts and theorems to unintended situations, keeping the synthetic proofs unmodified.”

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Classical Topology

(X, T_X)

X - set of points,

T_X - family of *open sets* of X

closed under:

finite intersection

arbitrary union

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(e.g. \mathbf{N} , \mathbf{R} , Σ)

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Classical Topology

Continuous functions, $f : (X, T_X) \rightarrow (Y, T_Y)$

Maps points forward

$$f : X \rightarrow Y$$

Maps open sets backwards

$$f^{-1} : T_Y \rightarrow T_X$$

Sierpinski Space

In what follows, Σ plays an important role.

$$\Sigma = \{ \top, \perp \}$$

$$\mathcal{T}_\Sigma = \{ \{ \}, \{ \top \}, \{ \top, \perp \} \}$$

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We'll think of Σ as **semidecidable truth values**. We'll think of functions into Σ as **semidecidable sets**.

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open sets of X

and

continuous functions from X to Σ .

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So topology is really just about continuous
functions into Σ . Topology is about
semidecidable sets.

Synthetic Topology

Ingredients for (synthetic) topology:

1. Spaces
2. Functions
3. Sierpinski Space

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Types

Functions

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Types are spaces, and each type has a built in “topology”, whose open sets correspond to the functions from that type into Σ .

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Σ must represent semidecidable truth values.

Sierpinski Type in NuPRL

$$\Sigma = (\mathbf{N} \rightarrow \mathbf{B}) // \sim$$

$$(f \sim g) \text{ iff } (\forall n. f\ n = \mathbf{ff}) \Leftrightarrow (\forall n. g\ n = \mathbf{ff})$$

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Semidecidable.

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(can't just do pointwise $\&\&$)

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Sierpinski Type

Countable join.

$\text{cjoin} : (\mathbf{N} \rightarrow \Sigma) \rightarrow \Sigma$

Requires LEMMA:

$\text{cjoin} = \text{dovetail}$

$X \subseteq \text{Base}$

$X \rightarrow (Y//E) \subseteq (X \rightarrow Y)//E'$

$\text{dovetail} : (\mathbf{N} \rightarrow \mathbf{N} \rightarrow \mathbf{B}) \rightarrow (\mathbf{N} \rightarrow \mathbf{B})$

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Given $f : X \rightarrow Y$ **All functions are**
 $A : \text{Open}(Y)$ **continuous.**

We get $A \circ f : \text{Open}(X)$ by composition.

Synthetic Topology

Intersection of opens \Rightarrow pointwise meet.

Union of opens \Rightarrow pointwise join.

Therefore:

Opens have finite intersections
and countable unions.

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Such that $(\exists X. A = \perp)$ iff $(\forall x. A x = \perp)$

Countable unions iff **N** is overt.

Compact Spaces

We also have **compact intersections**.

A space X is **compact** iff there is a function:

$$\forall X : \text{Open}(X) \rightarrow \Sigma$$

Such that $(\bigvee X.A = \top)$ iff $(\bigvee x. A x = \top)$

All finite sets are compact (and overt).

Compactness is dual to overtiness.

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Can we weaken this?

Subspaces

If $X \subseteq Y$ then X has a topology that is at least as fine as the subspace topology of Y , because $\text{Open}(Y) \subseteq \text{Open}(X)$.

X is an **open subspace** of Y iff there is a
 $A : \text{Open}(Y) \rightarrow \text{Open}(X)$ s.t. $X = \{ y : Y \mid A y = \top \}$.

Open Subspace vs Overt Subspace

If X is an open subspace of Y ,
and Y is overt,
then X is overt.

If X is an overt subspace of Y ,
and Y has semidecidable equality,
then X is an open subspace of Y .

Open Subspace vs Overt Subspace

If X is an open subspace of Y ,
and Y is overt,
then X is overt.

Not yet verified.
But simple proofs.

If X is an overt subspace of Y ,
and Y has semidecidable equality,
then X is an open subspace of Y .

Limitations

We don't have any **continuity principle**.

It should be the case that functions

$$(\mathbf{N} \rightarrow \mathbf{B}) \rightarrow \mathbf{B}$$

can depend only on finitely many values of the input. But that doesn't come for free.

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We probably can't show $(\mathbf{N} \rightarrow \mathbf{B})$ is compact.

We can't show opens on \mathbf{R} are “open sets”.

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We don't have **Markov's principle**.

We can't assume that just because

$$A \vee x \sim \top$$

then there must exist some $n : \mathbf{N}$ such that

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We don't have **Markov's principle**.

We can't assume that just because

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then there must exist some $n : \mathbf{N}$ such that

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This is probably incompatible with (weak) continuity principles.

Conclusion

We've taken the first steps to formalizing synthetic topology in NuPRL.

There is much work yet to do.

Especially:

- Looking at Tychonoff's theorem.

- Looking for something similar for overttness.